# UNICONT PMM-500 Universal process controller and display unit

User's and Programming manual 1<sup>st</sup> edition



Dodávateľ: MICROWELL, spol. s r. o. SNP 2018/42, 927 00, Šaľa TEL.:(+421) 31 770 7585 E-mail:microwell@microwell.sk

Manufacturer: **NIVELCO Process Control Co.** H-1043 Budapest, Dugonics u. 11. Phone: 889-0100 = Fax: 889-0200 E-mail: sales@nivelc.com = www.nivelco.com CE

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## Thank you for choosing a NIVELCO instrument. We are sure that you will be satisfied throughout its use!

# 1. GENERAL DESCRIPTION

The UNICONT PMM-500 universal display and controller instruments are 1/16 DIN (48x48mm) size, panel mountable, modern, easy of use microprocessor based devices supporting versatile functions. EEPROM memory ensures data- and program protection during power outages.

The universal input can be connected with wide range of temperature sensors (Pt-100 RTD-s and most type of thermocouples), or standard analogue current and voltage signals (mA, mV, V).

The instrument operates its control outputs in accordance to selected control algorithm generated from the measured input values of various physical parameters.

The control algorithm can be ON-OFF, or PID, therefore it can provide differential control, or can realize multiple control characteristics.

Using the Auto Tuning mode, the instrument provides optimal settings without entering any P-I-D parameters.

The controller has multiple outputs: relay, SSR-driver, analogue current-, or voltage output, RS485 communication. The modular structure provides wide selection of output variations. In accordance to the mechanical structure of the output boards (plug-in PCB-s) there is a possibility to order special (differing from the standard) variations.



The RS485 Modbus RTU serial output provides digital communication interface with PC and remote programming possibility.

Some models have 24V DC output performing power supply for transmitters.

The large bi-coloured 2-line, 7-segmented, 4-digit LED display provides easy reading even from far distance. It indicates the Process (PV) and a Set-point (SV) Value, as well the programming steps or other settings. Operation modes and alarm signals are indicated with LED-s. The 4 push-buttons provide easy programming.

# 2. ORDER CODE



#### UNICONT PMM-500 series: \* POWER SUPPLY CODE 100-240 V AC 1 20-48 V AC 2 22-65 V DC

OUTPUT*	CODE
R1, R2, analogue OUT	1
R1, R2, Ut	2
R1, analogue OUT, Ut	3
R1, R2, R3	4
SSR1, SSR2, analogue OUT	5
SSR1, SSR2, Ut	6
SSR1, analogue OUT, Ut	7
SSR1, R1, analogue OUT	8
R1, R2, analogue OUT, RS485	Α
R1, R2, Ut, RS485	В
R1, analogue OUT, Ut, RS485	С
R1, R2, R3, RS485	D
SSR1,SSR2, analogue OUT, RS485	Е
SSR1, SSR2, Ut, RS485	F
SSR1, analogue OUT, Ut, RS485	G
SSR1, R1, analogue OUT, RS485	Н

Ουτρυτ	DESCRIPTION
R1, R2, R3	SPDT relay outputs
analogue OUT	Analogue current- or voltage outputs
SSR1, SSR2	Solid State Relay driver output
Ut	Transmitter power supply 24 V DC/ 22 mA
RS485	Serial communication line

#### Accessories:

NAME	ORDER CODE
Mounting accessory	pmm5111m00001
Front plate sealing	pmm5111m00002
Front plate size adapter	
from 96x48 mm cut-off size to 48x48 mm	PAM-500-0

\* Special output versions differing from the above code-variations are available to order.

# 3. TECHNICAL DATA

Туре	Гуре РММ-5- <b>ОО-О</b>			
		Pt100 RTD: -199 °C+800 °C		
		Thermocouple: J, T, K, L, N, B, R,	S, C, Pt Rh	
	Sensor,	-240 °C+2320 °C		
	or analogue input	Current: (DC) 4-20 mA, 0-20 mA		
		Voltage: (DC) 0-50 mV, 10-50 r	nV,	
ŧ		0-5 V, 1-5 V, 0-1	0 V, 2-10 V	
лbг		Pt100 RTD: >10 MOhm,		
-	Input resistance	Current input (20 mA): 5 Ohm		
		Voltage input (10 V): 47 kOhm		
		Input Sampling rate: 4 / sec		
	Other data	Digital Input Filter time constant: 0	0.5100 sec	
Pt100 Sensor Current: 150 µA				
		Isolated from all outputs (except S	SR driver)	
	Relay	Max. 3 pcs., SPDT (Single pole double throw) 240 V AC, 2A, AC11		
	SSR	Max. 2 pcs., SSR (Solid State Rel	ay) driver, 0-10 V DC / 20 mA	
		4-20 mA, 0-20 mA / 500 Ohm max.		
ıts	Analamua DC	0-5 V, 0-10 V, 2-10 V/500 Onini min. Short-circuit protected		
ιtbr	Analogue DC	Accuracy: +0.25 %		
õ		Reinforced safety isolation from th	e input and other outputs	
	Transmitter nower	19-28 V DC not regulated Nomin	al value: 24 V DC / 22mA	
	supply	Reinforced safety isolation from th	e input and other outputs	
	Serial communication	RS485 MODBUS RTU, Address range: 1-255, Bit rate: 1200-19200 Baud		
		Features Operation range Resolution		
Con	rols:	Proportional Bands (P)	0.5-999.9%	0.1 %
ON/		Derivative Time Constant (D)	0 - 100 min	1 sec
P, P	D, PI, PID, Dual PID	Integral Time Constant (I)	1 sec - 100 min	1 sec
		Cycle Times	0.5 sec - 512 sec	binary steps
Cool	ing / Heating	ON/OFF Differential	0.1% - 10 % of input span	0.1 %
300	Deadband/Overlap -20 %+20 % of input span 0.1 %			

	7-segment LED	Process Value (PV): 4 digit, red, height of characters: 10 mm
ation	display	Set Value (SV): 4 digit, green, height of characters: 8 mm
		Operation modes:
		<ul> <li>Select mode, configuration</li> </ul>
di	I ED	<ul> <li>Automatic Tune</li> </ul>
드	LED	<ul> <li>Alarms</li> </ul>
		<ul> <li>Over-range indication</li> </ul>
		<ul> <li>Under-range indication</li> </ul>
Con	figuration	With press buttons of the front panel from -1999 to +9999 range
Mea	surement accuracy	±0.1% of range ±1LSD, Thermocouple: ±0.1% of full range span ±1LSD
Line	arization accuracy	Better than ±0.2°C any point, any 0.1°C range ( ±0.05°C typical). Better than ±0.5°C any point,
LING	anzation accuracy	any 1 °C range
Tem	perature stability	0.01% of range/°C change in ambient temperature
Sensor break protection		Process Control outputs turn OFF within two seconds
		In case of analogue input: applicable for 4 to 20mA, 1 to 5V and 2 to 10V ranges only
Cold junction compensation		>±1 ℃
Wire compensation		3-wire Pt100, automatic
Power supply		100-240 V AC 50/60 Hz 7.5 VA
1.04	ci suppiy	20-48 V AC 50/60 HZ 7.5 VA; 22-65 V DC 5 W
Elec	trical connection	Screw type terminals
Men	nory protection	Data stored in EEPROM
Elec	trical protection	Class II.
Ingr	ess protection	Front panel: IP66 Back panel: IP20
Amb	pient temperature	0 ℃+55 ℃
Stor	age temperature	-20 °+80 °C
Rela	tive humidity	Max. 85%
Dim	ensions	48 x 48 x 110 mm
Mas	s	~0.25 kg

# 4. DIMENSIONS

The unit can be mounted into a suitable 1/16DIN (48x48 mm) cutout place. Insertion length of the 48 unit is 110mm, the additional dimensions can be seen on the drawing below.



# 5. MOUNTING

The unit can be mounted with the help of the attached mounting accessory to the suitable cut-out hole. Be careful with the sealing, which provides proper sealing from the front panel. Suitable distances between multiple units should be taken into consideration.

The cut-out dimensions in case of single, or multiple units should be the following, and width of the mounting-plate is Lv=3-9 mm.

Using the optional PAM-500-0 front plate size adapter the 48x48mm sized unit can be mounted to an existing 96x48mm cut-out hole. In case of using the front plate size adapter, the width of the mounting-plate is Lv=3-5 mm



# 6. WIRING

#### 6.1 WIRING INSTRUCTIONS

POWER SUPPLY			
PMM-5□□ -1	PMM-5□□ -2	Notes: Connect the line voltage (live and neutral) as illustrated via a	
100-240 V AC	20-48 V AC	two-pole isolating switch (preferably located near the equipment)	
	22-65 V DC	and an anti-surge fuse.	
T1A	T365 mA	cable. The shield should be grounded at one end only.	
	IN O THAT	resistive leg and the common legs of the RTD (4-5 points) should be connected. OUT 1. OUT 2. OUT 2.	

# 6.2 WIRING CHART OF THE OUTPUT VERSIONS

	Outputs				
Туре	OUT1 OUT2 OUT3		OU	TA	
	1 2 3	13 14 15	16 17 18	11	12
PMM-511-□			Analogue — +		
PMM-512-□			24V DC / 22mA — +		
PMM-513-□		Analogue + —	24V DC / 22mA — +		
PMM-514-□					
PMM-515-□	SSR1 10V_DC / 20mA +	SSR2 10V_DC / 20mA	Analogue — +		
PMM-516-□	SSR1 10V_DC / 20mA +	SSR2 10V_DC / 20mA +	24V DC / 22mA — +		
PMM-517-□	SSR1 10V DC / 20mA +	Analogue + –	24V DC / 22mA - +		
PMM-518-□	SSR1 10V_DC / 20mA		Analogue — +		
PMM-51A-□			Analogue — +	RS4 B	185 A
PMM-51B-□			24V DC / 22mA — +	RS4 B	185 A
PMM-51C-□		Analogue 十 一	24V DC / 22mA — +	RS4 B	185 A
PMM-51D-□	R1			RS4 B	185 A
PMM-51E-□	SSR1 10¥ DC / 20 <u>m</u> A	SSR2 10¥ DC / 20mA	Analogue — +	RS4 B	185 A
PMM-51F-□	SSR1 10¥ DC / 20 <u>m</u> A	SSR2 10¥ DC / 20mA	24V DC / 22mA — +	RS4 B	185 A
	SSR1	Analogue	24V DC / 22mA	RS4	185
PMM-51G-□	10V DC / 20mA + —	+ -	- +	В	A
PMM-51H-□	SSR1 10V DC / 20mA + —	NO C NC	Analogue — +	B RS4	185 A

#### Wiring examples:

2-wire Pt 100 RTD, 1 relay output.



2-wire 4-20 mA transmitter, power supply for transmitter, 2 pcs. relay output.



3-wire voltage output transmitter, power supply for transmitter, 1 relay output, 1 analogue output.



# 7. FRONT PANEL, KEYPAD, DISPLAYS

The 7-segmented displays show the measured and set process values (Process Value-PV, Set Value-SV) in normal operation, and show text signals and values in accordance to the actual state of programming and configuration. With the 4 pushbuttons the menu-system can be handled and programming can be performed.



	Operation		
LED	<ul> <li>LIGHTS</li> </ul>	* FLASHES	
MAN	Setup mode	Manual mode	
ΔΤ	Auto tuning mode		
~	Self-Tune mode	Pre-Tune mode	
ALM	-	Alarm condition is present	
•	For Current Proportioned outputs, <b>ON</b> indicates primary power is >0% It turns <b>ON</b> when the stored Max. PV value is displayed on indicators	FLASHES in unison with Time Proportioning Primary outputs	
▼	For Current Proportioned outputs, <b>ON</b> secondary power is >0% It turns <b>ON</b> when the stored Min. PV value is displayed on indicators	FLASHES in unison with Time Proportioning Secondary outputs,	

After powering ON the unit performs an automatic self-test and flashes all front-plate LEDs for a moment. At first turning ON, or after replacing an output module **Coto ConF** indication can be seen on the display, which means that the unit should be configured in Configuration Mode (see 9.1, 10.2. points). In all other cases after the self-test the unit returns to normal operation mode.

# 8. ERROR MESSAGES AND INDICATIONS

ERROR DESCRIPTION	PV DISPLAY	SV DISPLAY
Configuration & Setup is required at <b>first</b> turn ON or if hardware configuration changed! Press button to enter configuration mode, then press a, or button to unlock code number, then press button to proceed. Configuration should be completed according to the configuration menu points.	Goto	ConF
Input more than 5% over-range 1	СННЭ	Normal display
Input more than 5% under-range 2	נוגז	Normal display
Sensor Break. Break detected in the input sensor or wiring	OPEN	Normal display
OUTPUT 1 error	Err I	OPn I
OUTPUT 2 error	Errz	0Pn2
OUTPUT 3 error	Err3	OPn3
OUTPUT A error	ErrA	0PnA

<sup>1</sup> If the PV display exceeds 9999 before 5% over-range is reached, an over-range indication is given.

<sup>2</sup> Indicators will allow up to 10% under-range on non-zero based Linear ranges. If the PV display is less than -1999 before the 5% under-range is reached, an under-range indication is given.

# 9. PROGRAMMING SEQUENCE

#### 9.1 POWERING UP FOR THE FIRST TIME



#### 9.2 SELECT MODE

## 9.2.1 MODE SELECTION SEQUENCE FOR PROGRAMMING



Hold down D button and press D button in any mode to enter Select Mode. Once in Select Mode, press or to select the required mode, then press to enter the chosen mode.

MODE	FUNCTION	PV DISPLAY	SV DISPLAY
Operator mode	The Default Mode on power up used for normal operation	OPtr	SLCE
	Unlock code	noi	ne
Set-up mode	Used to tailor the instrument to the application, adjustment of tuning terms etc.	SELP	SLCE
	Unlock code	Default value: 5	ULoc
Configuration	Used to configure the instrument for first time use or on re-installation.	ConF	SLCE
mode	Unlock code	<b>D</b> Default value: 5	ULoc
Production Information mode	Production Used to check the hardware, firmware and and manufacturing information of the instrument		SLCE
	Unlock code	noi	ne
	Used to invoke pre-tune or self-tune on controllers.	Atun	SLCE
Auto Tuning mode	Unlock code	Default value: O	ULoc

If there is no key activity for 2 minutes the controller automatically returns to operator mode!

#### 9.2.2 UNLOCK CODE

To enter a required menu point press button then select the corresponding unlock code with an and buttons. This procedure can prevent unauthorised entry to Configuration, Setup and Automatic Tuning modes. Entering an incorrect unlock code will result to return to Select Mode. The value of the lock codes only can be changed from within the modes that they apply to.

In the event that a lock code is not known or forgotten, the instrument lock code values can be seen in the lock code view. In this view the codes are read only, the codes can be changed from the mode to which they apply.

Turn OFF the device. Press and together whilst the instrument is powering up until the display is shown. Once in this mode press to step between lock codes.

LOCK CODE NAME	PV DISPLAY	SV DISPLAY
Configuration Lock Code	Max. 4 digit value, DEFAULT VALUE: 5	[Loc
Setup Lock Code	Max. 4 digit value, DEFAULT VALUE: 5	SLoc
Automatic Tune Lock Code	Max. 4 digit value, DEFAULT VALUE: 0	ŁLoc

If there is no key activity for 2 minutes the controller automatically returns to operator mode!



## **10.1 INFORMATION MODE**

This mode describes the instrument and the options fitted to it. It is advised to start Select Mode procedure with this point because toggling in the menu, hardware configuration, manufacturing data can be seen about the given instrument.



Parameters are read only!

If there is no key activity for 2 minutes the controller automatically returns to operator mode!

PARAMETER	POSSIBLE VALUES	PV DISPLAY	SV DISPLAY	
Input type	Universal input	Uni	ln_ l	
	No option fitted	nonE		
Option 1 module type	R1 Relay	rL9	oPni	
	SSR1 drive	SSr		
	No option fitted	nonE		
Option 2 modulo type	R2 Relay	rL9	-0-2	
Option 2 module type	SSR2 drive	SSr	orne	
	Linear voltage / current output	Lm		
	No option fitted	nonE		
Option 3 modulo type	R3 Relay	rL9	-0-3	
Option 5 module type	Linear voltage / current output	Lm		
	24V Transmitter power supply dc24			
Auxiliany option A modulo type	No option fitted	nonE	_0_0	
Auxiliary option A module type	RS485	r485		
Firmwore	Type number	4 characters	FLL	
Filliwale	Issue number	2 characters	155	
Product Rev Level	Interior code	4 characters	PrL	
Date of manufacture	Interior code	4 characters	9000	
		4 characters	Sn I	
Serial number	Interior code	4 characters	5n2	
		4 characters	5n3	

#### **10.2 CONFIGURATION MODE**

This mode is normally used only when the instrument is configured for the first time or when a major change is made to the instruments characteristics. The Configuration Mode parameters must be set as required before adjusting parameters in Setup Mode, or attempting to use the instrument in an application. *Navigating in Configuration Mode* 



Caution:

- Entering an incorrect unlock code will result to return to Select Mode. Only parameters that are
  applicable to the hardware options chosen will be displayed.
- Once the value is changed, the display will flash to indicate that confirmation of the change is required. The value will revert back if not confirmed within 10 seconds.
- If there is no key activity for 2 minutes the controller automatically returns to operator mode!

PARAMETER		SV- DISPLAY	PV- DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE
		InPt	60	B tip. 1001824 °C	PEC
			ЪF	B tip. 2113315 °F	
			ננ	C tip. 02320 °C	
			CF	C tip. 324208 °F	
			JC	J tip200120 °C	
			JF	J tip3282192 ° F	
			J.C	J tip188,8537,7 °C	
			J.F	J tip199,9999,9 °F	
			PC	K tip2401373 °C	
			PF	K tip4002503 °F	
			P L	K tip128,8537,7 °C	
7	Φ		P }-	K tip199,9999,9 °F	
ean	Idno			L tip. 0762 °C	
type	1000		<u>.</u>	L tip. 321403 °F	
Put R	Jern			L tip.0,0537,7 °C	
-	F			L lip. 52,0999,9 F	
				N tip. 32, 2551 °F	
				R tip. 0, 1759 °C	
			-F	R tip 32 3198 °F	
			Sr	S tin 0 1762 °C	
			55	S tip. 32 3204 °F	
			ы	T tip240400 °C	
			FF	T tip400752 ° F	
			ΕĹ	T tip128,8400,0 °C	
			F F	T tip199,9752,0 °F	
			P24C	PtRh tip. 01850 °C	
			PZYF	PtRh tip. 323362 °F	
			PEC	Pt100: -199800 °C	
	8		PEF	Pt100: -3281472 °F	
	Æ		PE [	Pt100: -128,8537,7 °C	
			PL F	Pt100: -199,9999,9 °F	
P			0-20	0-20 mA DC	
ge ge			4-20	4-20 mA DC	
Ran			0-50	0-50 mV DC	
lnpu	ane		10.50	10-50 mV DC	
	nalo		0-5	0-5V DC	
	A		1-5	1-5 V DC	
			0-10	0-10 V DC	
			2-10	2-10 V DC	
Scale Rang	е	ruL	Scale Range	e Lower Limit +100 to Range Max	Linear inputs
Upper Limit			Between -19	999+9999	= 1000 (°C/°F
					range)
					• •
Scale Rang	е	rll	Range Min.	to Scale range Upper Limit -100	Linear = 0
Lower LITTIL			Detween - 15	JJJJ+JJJJJ	(°C/°F = min
					.u.igo).
Decimal no	int position	dPoS	n	No decimal point	1
(Only for	analogue	5.05	1	XXX.X	1
input)	-		ż	XX.XX	
			3	X.XXX	1

SV- DISPLAY	PV- DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE
CFAb	Snûl	Single outputs can drive the PV in one direction only (e.g.	Snûl
	d. 81	Dual outputs can force the PV to increase or decrease	
	DUNL	(e.g heat & cool, humidify and dehumidify etc)	
[ErL	rEu	Reverse action is typically used with heating applications; On-Off reverse outputs will turn off when the process variable exceeds setpoint. Proportional reverse outputs will decrease the percentage of output as the process value increases within the proportional band. The Secondary Output will be direct whenever the Primary Output is selected as reverse.	rEu
	d r	Direct action is typically used with cooling applications; On-Off direct outputs will turn on when the process variable exceeds setpoint Proportional direct outputs will increase the percentage of output as the process value increases within the proportional band. The Secondary Output will be reverse whenever the Primary Output is selected as direct.	
ALA I	P_Lo	Process High Alarm Reverse action OUT OFF ALM OFF ON Alarm PV Direct action OUT OFF ON Alarm PV Process Low Alarm Reverse action OUT OFF ON Alarm PV Direct action OUT OFF ON Alarm PV Direct action OUT OFF ON Alarm PV Direct action OUT OFF ON Alarm PV	Р_Н ,
	SV. DISPLAY CEYP CErL	SV- DISPLAY DISPLAY CEYP SnGL duAL CErL rEu dur ALA I P_H , P_Lo	SV- DISPLAY         PV- DISPLAY         ADJUSTMENT RANGE           CEYP         Sr.GL         Single outputs can drive the PV in one direction only (e.g. heat only, cool only, increase humidity etc)           duRL         Dual outputs can force the PV to increase or decrease (e.g. heat Scoto, humidity and dehumidity etc)           CErL         r.Eu         Reverse action is typically used with heating applications; On-Off reverse outputs will turn off when the process variable exceeds setpoint. Proportional reverse outputs will arceases within the proportional band. The Secondary Output will be direct whenever the Primary Output is selected as reverse.           d r         Direct action is typically used with cooling applications; On-Off direct outputs will turn on when the process variable exceeds setpoint. Proportional direct outputs will increase the percentage of output as will process value increases within the process value increases within the process value increases within the proportional direct outputs will increase the percentage of output as the process value increases within the proportional band. The Secondary Output will be exceeds setpoint. Proportional band. The Secondary Output will be reverse whenever the Primary Output is selected as direct.           RLR I         P.H r         Process High Alarm Reverse action           OUT OFF ON         Alarm PV         Direct action           ULT OFF ON         Alarm PV         Direct action           OUT OFF ON         Alarm PV         Direct action

PARAMETER	SV- DISPLAY	PV- DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE
		đE	Deviation Alarm <u>Up</u> Reverse action OUT ON OFF ALM OFF Alarm → + + Direct action OUT OFF ON ALM OFF PV Alarm → +	
			Down Reverse action OFF ALMON OFF - CAlarm PV	
		- 0 -	Direct action	
		bfind	Hand Alarm Reverse action	
			Direct action	
Process High		Range Min	No alarm	Range
Alarm 1 value Only visible when <b>ALA I = P_H</b> iset Parameter is repeated in Set-up Mode		nange Will.	a sanga mas.	Max.
Process Low Alarm 1 value Only visible when <b>ALA 1 = P_Lo</b> set Parameter is repeated in Set-up Mode	pla i	Range Min.	to Range Max.	Range Min.

PARAMETER	SV- DISPLAY	PV- DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE
Deviation Alarm 1 Value Only visible when <b>RLR I = dE</b> set Parameter is repeated in Set-up Mode	dAL I	±span from :	setpoint	5
Band Alarm 1 Value Only visible when <b>RLR I = bRnd</b> set Parameter is repeated in Set-up Mode	bal I	1 LSD to full	span from setpoint	5
Alarm 1 Hysteresis Parameter is repeated in Set-up Mode	Яну I	Up to 100% of span	Alarm hysteresis Process High Alarm or Deviation Alarm OFF OF OF OF OF OF Value Process Low Alarm or Deviation Alarm Process Low Alarm or Deviation Alarm Process Low Alarm or Deviation Alarm OFF ON OFF Alarm Hysteresis Value Band Alarm	1
Alarm 2 Type	ALA2	P_H , P_Lo dE bAnd	As for Alarm 1. As for Alarm 1. As for Alarm 1. As for Alarm 1. As for Alarm 1.	P_Lo
Process High Alarm 2 Value Only visible when <b>RLR2 = P_H</b> iset Parameter is repeated in Set-up Mode	Ph82	Range Min. 1	l na rozmeni t. lo Range Max	Range max.
Process Low Alarm 2 Value Only visible when <b>RLR2</b> = <b>P_Lo</b> set Parameter is repeated in Set-up Mode	PLA2	Range Min. t	o Range Max	Range min.

PARAMETER	SV- DISPLAY	PV- DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE
Deviation Alarm 2 Value Only visible when <b>ALA2</b> = <b>dE</b> set Parameter is repeated in Set-up Mode	dRL2	±span from s	setpoint	5
Band Alarm 2 Value Only visible when <b>ALR2 = bAnd</b> set Parameter is repeated in Set-up Mode	PAT5	1 LSD to full	span from setpoint	5
Alarm 2 Hysteresis Parameter is repeated in Set-up Mode	AH75	1 LSD to 100% of span (in display units) on "safe" side of alarm point	As for Alarm 1.	1
Loop Alarm Enable	LREn	Disabled: J SA Enabled: EnAb	Loop Alarm A loop alarm is a special alarm, which detects faults in the control feedback loop, by continuously monitoring process variable response to the control output(s). The loop alarm can be tied to any suitable output. When enabled, the loop alarm repeatedly checks if the control output is at the limit, an internal timer is started: thereafter, if the high output has not caused the process variable to be corrected by a predetermined amount V after time T has elapsed, the loop alarm becomes active. Subsequently, the loop alarm mode repeatedly checks the process variable starts to change value in the correct sense or when the output is no longer at the limit, the loop alarm is deactivated. For PID control, the loop alarm time T is always twice the Automatic Reset parameter value. For On-Off control, a user defined value for the Loop Alarm Time parameter is used. The value of V is dependent upon the input type. For Temperature inputs, V = 2°C or 3°F. For Linear inputs, V = 10 least significant display units. Control output limits are: • 0% for Single output (Primary and Secondary) controllers Correct operation of the loop alarm depends upon reasonably accurate PID tuning. The loop alarm from manual mode or after completion of the Pre-Tune routine, the loop alarm is automatically re-enabled.	d .5A

PARAMETER	SV- DISPLAY	PV- DISPLAY		Α	DJUSTME	NT RANG	iΕ		DEFAULT VALUE
Loop Alarm Time Only visible when <b>LREn = EnRb</b> set Parameter is repeated in Set-up Mode	LAF 1	1 sec to 99 n Only applies	nins. 59seo if primary	s proportion	al band <b>P</b>	<b>6_P</b> =0			99.59
Alarm Inhibit	inh i	nonE	No alarr	ns Inhibite	d				nonE
		ALA I	Alarm 1	inhibited					
		ALA5	Alarm 2	inhibited					
		both	Alarm 1	and alarm	n 2 inhibite	d			
Output 1 Usage	USE I	Pri	Primary	Power					Pri
Only visible when		SEc	Second	ary Power	if CLYP	- duAL			
		R I_d	Alarm 1	, Direct Ac	ting				
		R I_r	Alarm 1	, Reverse	Acting				
		P-28	Alarm 2	, Direct Ac	ting				
		<u>n_58</u>	Alarm 2	, Reverse	Acting				
		LP_d	Loop Al	arm, Direc	t Acting				
			Loop Al	arm Rever	se				
			LOOP AI	arm, Reve	rse Acting				
		OR Alarm		Logic	Alami I. C	ations of A	larme		
		2.		Direct			Reverse		
		Direct	Alarm	Alarm	OUT	Alarm	Alarm	OUT1	1
			1	2	1	1	2		
		Ortr	OFF	OFF	OFF	OFF	OFF	ON	
		Alarm1	OFF	OFF	ON	ON	OFF	OFF	
		2.	ON	ON	ON	ON	ON	OFF	
		Reverse							
		Rd_d			Alarm1. Al	ND Alarm 2	2		
		Alarm1.		Direct			Reverse		
		AND	Alarm	Alarm	OUT	Alarm	Alarm	OUT1	
		Direct	OFF	OFF	OFF	OFF	OFF	ON	
		Rd c	ON	OFF	OFF	ON	OFF	ON	
		Alarm 1.	OFF	ON	OFF	OFF	ON	ON	
		AND	ON	ON	ON	ON	ON	OFF	
		Alarm 2.							
Output 2 Usage	11562	Pe .	Primany	Power	1	1	1	1	82 4
Only visible when	JUL	SEc	Second	any Power	і <b>г ГРЧР</b>	- duAl			
oPn2 ≠ nonE		BLA	Alarm 1	Direct Ac	tina				
		Blc	Alarm 1	. Reverse	Actina				
		82_d	Alarm 2	, Direct Ac	ting				
		R2_r	Alarm 2	, Reverse	Acting				
		LP_d	Loop Al	arm Direct	Acting				
		LP_r	Loop Al	arm Revei	rse Acting				
		Or_d	Logical	combinatio	ons of Alar	ms			
		Alarm1	<u> </u>	D:	Alarm 1. C	R Alarm 2			
		OR Alarm2	Alarm	Direct	OUT	Alarm	Alarm	OUT?	1
		Direct	1	2	2	1	2	0012	
		Or_r	OFF	OFF	OFF	OFF	OFF	ON	1
		Alarm1	ON	OFF	ON	ON	OFF	OFF	
		OR	OFF	ON	ON	OFF	ON	OFF	
		Reverse	ON	ON	ON	ON	ON	OFF	

PARAMETER	SV- DISPLAY	PV- DISPLAY		A	DJUSTME	ENT RANG	Ε		DEFAULT VALUE
		Ad_d	Alarm1. és (AND) Alarm 2.						
		Alarm1		Direct			Reverse		]
		AND	Alarm	Alarm	OUT	Alarm	Alarm	OUT2	
		Alarm2 Direct	1	1	2	1	1	055	{
			ON	ON	OFF	OFF	OFF	OFF	
		Alarm1	OFF	OFF	OFF	OFF	OFF	OFF	{
		AND	ON	ON	ON	ON	ON	ON	
		Alarm2				-	-	-	
		Reverse							
		rELS	Retrans	mit SP or	PV Output	tif			
		rELP	oPnd	=Lin					
Linear Output 2 Range	FAbs	0-5	0-5V D0	COUT2.					0-10
Only visible when		0-10	0-10V E	OC OUT2.					
orne = L in		2- IO	2-10V D	OC OUT2.					
		0-20	0-20 m/	A DC OUT:	2.				
		4-20	4-20 m/	A DC OUT:	2.				
Retransmit Output 2	roZH	It may be ad	justed with	in the ran	ge -1999 i	to 9999; th	ne decimal	position	Range
Scale maximum Only visible when		is always the	e same as	that for t	he proces	s variable	input. If <b>r</b>	-0 IH <	max.
IISE2 - cEFS or		ro IL, the r	elationship	between	the proces	s variable	/setpoint v	alue and	
CELP		the retransm	ission outp	ut is rever	sed.				
Retransmit Output 2	co21	It may be ad	liusted with	in the ran	ae -1999	to 9999: th	ne decimal	position	Range
Scale minimum		is always the	e same as	that for t	he proces	s variable	input. If <b>r</b>	-o IH >	min.
Only visible when		coll the n	elationshin	hetween	the proces	s variable	/setnoint v	alue and	
USE2 = rEtS or		the retransm	ission outp	ut is rever	sed.		ootpoint i		
rELP									
Output 3 Usage	USE3	Prl	Primary	Power					RI_d
		SEc	Second	ary Power	if CLYP	= duAL			
0 - 11 3 7 0 2 2 1		A I_d	Alarm 1	, Direct Ac	ting				
		A L_r	Alarm 1	, Reverse	Acting				
		P_28	Alarm 2	. Direct Ac	ting				
		7_5R	Alarm 2	Reverse A	Acting				
		UP_d	Loop Al	arm Direct	Acting				
			Loop Al	arm Rever	se Acting				
		Ur_d Alarm1	Logical	combinatio	ons of Alar	ms			
		OR			Alarm 1. C	R Alarm 2	2.		
		Alarm2 Direct		Direct			Reverse		]
		Direct	Alarm	Alarm	OUT	Alarm	Alarm	OUT3	
			1	2	3	2	1	011	
		Ur_r Alorm1	OFF	OFF	OFF	OFF	OFF	OFF	ł
		OR	OFF	ON	ON	OFF	ON	OFF	ł
		Alarm2	ON	ON	ON	ON	ON	OFF	ł
		Reverse							
		Ad_d		1	Alarm1. Al	ND Alarm 2	2.		
		AND		Direct			Reverse		ļ
		Alarm2	Alarm	Alarm	OUT	Alarm	Alarm	OUT3	
		Direct	1	2	3	1	2	055	ł
			ON	ON	ON	ON	ON	ON	1
		Alarm1	OFF	OFF	OFF	OFF	OFF	OFF	ł
		AND	ON	ON	ON	ON	ON	ON	í
		Alarm2							
		Reverse							

PARAMETER	SV- DISPLAY	PV- DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE				
		rEtS	Retransmit SP or PV Output if					
		rELP	oPn3=Lin					
Output 3 PV	FRb3	0-5	0-5 V DC OUT3	0-10				
Retransmit Type		0-10	0-10 V DC OUT3					
Only visible when		2- IO	2-10 V DC OUT3					
orng = L in		0-50	0-20 mA DC OUT3					
		4-20	4-20 mA DC OUT3					
Retransmit Output 3	ro3H	It may be ad	justed within the range -1999 to 9999; the decimal position	Range				
Scale maximum		is always the	e same as that for the process variable input. If $ro$ IH <	max.				
Only visible when		ro IL, the r	elationship between the process variable/setpoint value and					
		the retransm	ission output is reversed.					
	-			5				
Retransmit Output 3	rodL	It may be ad	It may be adjusted within the range -1999 to 9999; the decimal position					
visible when		is always the	e same as that for the process variable input. If ro in >					
USER = cEFS or		ro IL, the r	elationship between the process variable/setpoint value and					
CEFP		the retransm	ission output is reversed.					
Display Strategy	d ISP	1, 2, 3, 4,	1. 2. 3. 4. see Operator Mode for details					
., .,	• • • •	5,6						
Communication	Prot	րվես	Modbus with no parity	በባይካ				
Protocol		ГЛЬЕ	Modbus with Even Parity					
Configured for OUT A		ГЛЬо	Modbus with Odd Parity					
Bit rate	bBud	12	1200 Baud	4.8				
Only visible when	0000	2.4	2400 Baud	4.0				
oPnA = r485		2.4	2400 Baud					
		9.6	9600 Baud					
		19.2	19200 Baud					
Communication Address	Addr	1	A unique address for each instrument between 1 to 255	1				
Communications Write	CoEn	ուսվ	r_اس Read / Write. Writing via Comms is possible					
Enable		r_0	Read only. Comms writes ignored					
Configuration Mode Lock Code	CLoc	Selectable b	etween 09999	5				

## 10.3 SET-UP MODE

This mode is normally selected only after Configuration Mode has been completed, or is used when a change to the process set up is required. These parameters must be set as required before attempting to use the indicator in an application.

When in Set-up Mode, the MAN LED indicator flashes.

#### Navigating in Set-up Mode:



Caution:

- Entering an incorrect unlock code will result to return to Select Mode.
- Only parameters that are applicable to the hardware options chosen will be displayed.
- Once the displayed value is changed, it is effective and immediately. No confirmation of the change is required.
- If there is no key activity for 2 minutes the controller automatically returns to operator mode!

PARAMETER	SV- DISPLAY	PV-DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE		
Input Filter Time constant	Filt	This parameter is used process variable. The f functions (display cont adjustable from 0.0 se second increments.	2.0			
Process Variable Offset	OFFS	±Span of controller betv	/een -999+999	0		
Primary Power	PPUJ	The current Primary Out	The current Primary Output Power. Read Only			
Secondary Power	SPLJ	The current Secondary	N/A			
Only visible when CESP = duAL set						
Primary Output Proportional Band (P)	РЬ_Р	0.0% (ON/OFF control)	10.0			
Secondary Output Proportional Band (P)	РЬ_5	0.0% (ON/OFF control)	and 0.5% to 999.9% of input span	10.0		
Only visible when CLYP = duAL set						
Automatic Reset (Integral Time Constant) (I) Only visible when <b>Pb_P</b> ≠0.0	Arst	0.01 to 99.59 (1 sec to 9 OFF=0.00	9 mins 59 secs)	5.00		
Rate (Derivative Time Constant) (D) Only visible when $Pb_{-}P \neq 0.0$	rAFE	0.00 to 99.59 (OFF to 99	) mins 59 secs)	1.15		

PARAMETER	SV- DISPLAY	PV-DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE
Overlap/Deadband Only visible when Pb_P ≠ 0.0 or CLYP = duRL	DL	Defines the portion of the primary and secondary proportional bands (Pb_P + Pb_S) over which both outputs are active (Overlap), or neither is active (Deadband)	OUT OUT2. (positive value) OUT2. (positive value) OUT1. (positive value) OUT2. (negative value)	0
		It is adjustable in the range -20% to +20% of the two proportional bands added together.		
Manual Reset (Bias) Only visible when <b>Pb_P</b> ≠.0.0	ь <b>,</b> Я5	0% to 100% (-100% to 1 Used to manually bias t for process load variatio output power and is ac Primary Output alone) of Secondary Outputs).	100% if <b>LEYP</b> = <b>duRLJ</b> he proportional output(s) to compensate ns. Bias is expressed as a percentage of ijustable in the range 0% to 100% (for r -100% to +100% (for both Primary and	25
Primary Output ON/OFF Differential Only visible when <b>Pb_P</b> =0.0	d 'Eb	0.1% to 10.0% of input s	span (enter in % span).	0.5
Secondary Output ON/OFF Differential Only visible when <b>Pb_5</b> =0.0	d (FS	0.1% to 10.0% of input s Differential band is sym	span (enter in % span). netric to Setpoint Value.	0.5
Primary and Secondary Output ON/OFF Differential Only visible when <b>Pb_P</b> =0.0 and <b>Pb_S</b> =0.0	d FF	0.1% to 10.0% of input s Differential band is sym	span (enter in % span) metric to Setpoint Value.	0.5
Setpoint Upper Limit	SPul	Current Setpoint value t	o Scale Range Maximum	Range max.
Setpoint Lower limit	SPLL	Scale Range Minimum t	o current Setpoint value	Range min.
Primary (Heat) Output Upper Power Limit Only visible when <b>Pb_P</b> ≠0.0	OPuL	0% to 100% of full powe	ſ	100
Output 1 Cycle Time Only visible when USE I = Pr + or USE I = SEc	CE 1	For time proportioning over which the average PID output level. <b>CE 1</b> , are defined as time por seconds. Shorter cycle expense of reduce life control device (e.g. relay For example Proportional Band <b>Pb_P</b> =25%, Cycle Time: <b>CE</b> =32 sec, then 100%/25% =4 ON=32/4 = 8 sec. OFF= 32-8=24 sec.	outputs, it is used to define time period on vs. off time is equal to the required is available when option slots 1, 2 or 3 oportioning output types. The permitted 1, 2, 4, 8, 16, 32, 64, 128, 256 or 512 times will give better control, but at the when used with an electromechanical ys or solenoid valves).	32

PARAMETER	SV- DISPLAY	PV-DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE
Output 2 Cycle Time Only visible when USE2 = Pr , or USE2 = SEc	CF5	0.5, 1, 2, 4, 8, 16, 32, 64 Not applicable to linear of	I, 128, 256 or 512 secs. outputs.	32
Output 3 Cycle Time Only visible when USE3 = Pr •, or USE3 = SEc	CF3	0.5, 1, 2, 4, 8, 16, 32, 64 Not applicable to linear	I, 128, 256 or 512 secs. outputs.	32
Process High Alarm 1 Value Only visible when <b>ALA</b> I= <b>P</b> + vet Parameter is repeated in Configuration Mode	РҺА І	Range Min. to Range M	ax.	Range max.
Process Low Alarm 1 Value Only visible when <b>ALA I = P_Lo</b> set Parameter is repeated in Configuration Mode	PLA I	Range Min. to Range M	ax.	Range min.
Deviation Alarm 1 Value Only visible when <b>ALA 1 = dE</b> set Parameter is repeated in Configuration Mode	dal I	±span from setpoint between -999+999		5
Band Alarm 1 Value Only visible when <b>ALA I = bAnd</b> set Parameter is repeated in Configuration Mode	lal i	1 LSD to full span from s between 1999	setpoint	5
Alarm 1 Hysteresis Parameter is repeated in Configuration Mode Process High Alarm 2 Value	Яну I	Up to 100% of span between 1999	Alarm Hysteresis Process High Alarm or Deviation Alarm OFF ON OFF Alarm Value PV Alarm Value Pv OFF ON OFF Alarm Value Value Pv OFF ON OFF Alarm Value or Deviation Alarm Value Alarm Value or Deviation Alarm Value or	Danne
All of the when ALR2 = P_H i set Parameter is repeated in Configuration Mode	PhHc	Range min. to rearige m	ax.	Range max.
Process Low Alarm 2 Value Only visible when <b>RLR2 = P_Lo</b> set Parameter is repeated in Configuration Mode	PLR2	Range Min. to Range M	ax.	Range min.

PARAMETER	SV- DISPLAY	PV-DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE
Deviation Alarm 2 Value Only visible when <b>ALA2</b> = <b>dE</b> set Parameter is repeated in Configuration Mode	94r5	±span from setpoint		5
Band Alarm 2 Value Only visible when <b>ALAZ = bAnd</b> set Parameter is repeated in Configuration Mode	PUL5	1 LSD to full span from setpoint		5
Alarm 2 Hysteresis Parameter is repeated in Configuration Mode	8H75	1 LSD to 100% of span (in display units) on "safe" side of alarm point	As for Alarm 1.	1
Loop Alarm Time Only visible when <b>LREn = EnRb</b> set Parameter is repeated in Configuration Mode	LAE I	1 sec to 99 mins. 59secs Only applies if primary proportional band <b>Pb_P</b> =0		99.59
Auto Pre-tune enable / disable P <b>B_P</b> , or <b>PB_S</b> ≠ 0.	<i>₽₽</i> £	<b>d</b> .5R disabled EnRb enabled Auto Pre-Tune is useful when the process to be controlled varies significantly each time it is run. Auto Pre-Tune ensures that tuning occurs at the start of the process. Self-Tune may also be engaged to fine tune the controller. AT LED indirector flashes		d 15A
Manual Control select enable / disable	PoEn	Instant Device           ISR disabled           EnAb         enabled, MAN LED indicator flashes.           PV display: shows measured process value.           SV display: shows PXXX, where X values are % of the output, adjustable           by B and B buttons, for primary output: between 0 - 100 %, for orimary and secondary output.		d 15A
Setpoint ramp shown in operator mode, enable / disable	58-	d ISA disabled		d iSA
Setpoint Ramp Rate Value	٢P	The ramp rate may be adjusted in the range 1 to 9999 and OFF. Increasing the ramp rate value beyond 9999 will cause the upper display to go blank and setpoint ramping to be switched OFF. Setpoint ramping can be resumed by decreasing the ramp rate to 9999 or less. The actual setpoint will rise/fall at the ramp rate set, until it reaches the target setpoint value. Setpoint ramping is used to protect the process from sudden changes in the setpoint, which would result in a rapid rise in the process variable.		OFF
Setpoint Value	SP	Within scale range upper and lower limits		Range min.
Set-up Lock Code	SLOC	0 to 9999		5

## 10.4 AUTO-TUNING (AT) MODE

Automatic Tune Mode is selected when it is desired to use the Pre-tune and Self-tune facilities on a controller to assist the user in setting up Proportional band, Integral and Derivative parameter values. Refer to the following Automatic Tune Mode table.

#### Navigating in Automatic Tune Mode:



Caution:

- Entering an incorrect unlock code will result to return to Select Mode.
- If there is no key activity for 2 minutes the controller automatically returns to operator mode!

PARAMETER	SV- DISPLAY	PV-DISPLAY	ADJUSTMENT RANGE	DEFAULT VALUE
PRE-Tune Auto Pre-Tune ensures that first approximation of the PID values can be made. Auto Pre-Tune feature is activated on power up if <b>APL</b> = <b>EnRb</b> set.	Ptun	OFF or ON Indication remains OFF if Pre-Tune cannot be used at this time. This applies if: a). The setpoint is ramping b). The process variable is less than 5% of span from the setpoint c). The primary or secondary output proportional bands = 0 AT LED indicator flashes if PRE-Tune is ON		OFF
SELF-Tune Self-Tune continuously optimises tuning while a controller is operating	Stun	OFF or ON Indication remains OFF if Self-Tune cannot be used at this time. This applies if either proportional band = 0 AT LED indicator continuously lights if SELF-Tune is ON		OFF
Approximation of the PID values then continuous optimising PRE-Tune + SELF-Tune ON	Ptun then Stun	PLun = ON SLun = ON under PLun AT LED indicator flashes, then during SLun AT LED continuously lights		OFF
Automatic tune mode lock code	tLoc	0 to 9999		0

#### **10.5 MANUAL SETTING OF PID PARAMETERS**

If Auto Tuning mode is not enabled, controlling can be manually tuned. Manual setting of PID parameters is suitable only for processes that are not harmed by large fluctuations in the process variable. This technique needs technical competence and practise in process controlling, therefore changing of the parameters are allowed only if regulating system surely remains its safe operation.

All parameters should be set in Configuration and Set-up Modes before manual tuning of PID parameters!

#### Single Control Tuning (PID with Primary Output only) - cooling, or heating

 In Configuration mode select Single control type Primary control

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Select Setpoint Value in Operator Mode in accordance to the process.

- Check that the Setpoint Upper Limit (SPLL) and Setpoint Lower Limit (SPLL) are set to safe levels for the process. Adjust if required
- Select ON-OFF control (**Pb\_P**=0)
- Switch on the process. The process variable will oscillate about the setpoint.



Record the Peak-to-Peak variation (P) of the first cycle (i.e. the difference between the highest value of the first overshoot and the lowest value of the first undershoot), and the time period of the oscillation (T) in minutes:

Primary Proportional Band (P):

Integral Time Constant (I): Derivative Time Constant (D): Pb\_P= <u>P</u> (SPuL - SPLL) ×100 ArSt= T [min] rAtE= T/6 [min]

In Set-up Mode select PID parameters in accordance to the calculation using the formula above.

#### Dual Control Tuning (PID with Primary and Secondary Outputs) - cooling and heating

 In Configuration mode select Dual control type Primary and Secondary control

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- Select Setpoint Value of Primary output as described above.
- Set Pb\_5 to the same value as Pb\_P and monitor the operation of the controller in dual control mode.
- If there is a tendency to oscillate as the control passes into the Secondary Proportional Band, increase the value of **Pb\_5**.
   If the process appears to be over-damped in the region of the Secondary Proportional Band, decrease the value of **Pb\_5**.
- When the PID tuning values have been determined, if there is a kick to the process variable as control
  passes from one output to the other, set the Overlap/Deadband **QL** parameter to a positive value to
  introduce some overlap.

Adjust this value by trial and error until satisfactory results are obtained.

#### **10.6 MANUAL FINE TUNING OF PID PARAMETERS**

- Adjustment of Cycle Time (Lt) parameter (in Set-up Mode) is provided for each time proportioning control output. Take into consideration that a shorter cycle time gives more accurate control but electromechanical components such as relays have a reduced life span.
- Increase the width of the proportional band if the process overshoots or oscillates excessively.
- Decrease the width of the proportional band if the process responds slowly or fails to reach setpoint.
- Increase the automatic reset (*RrSt*) (Integral Time Constant) until the process becomes unstable, and then decrease until stability has been restored.
- Modify Integrate Time to between 10-25% of the previous value. If the process overshoots or oscillates
  excessively, decrease its value.
- After making all other adjustments, if an offset exists between the setpoint and the process variable use the Bias b IRS (manual reset) to eliminate the error. When PV is below SV use a larger bias value, when PV is above SV use a smaller bias value.

## **10.7 OPERATOR MODE**

This is the normal operating mode of the instrument from power-up. It can also be accessed from any other mode via Select Mode as follows.

In order to provide proper operation, all parameters should be configured in the Configuration Mode and Set-up Mode before using the Operator Mode!

From any Mode if there is no key activity for 2 minutes the controller automatically returns to operator mode!

Display mode is in accordance to the selected value in Configuration Mode  ${\it d}$  ,5P parameter between 1...6.

Toggle between PV and SV can be performed with  $\ensuremath{\mathfrak{O}}$  button and values can be modified with  $\ensuremath{\mathfrak{O}}$ , or  $\ensuremath{\mathfrak{O}}$  buttons.



#### 10.7.1 DISPLAY MODES

The required display mode can be selected in Configuration Mode. Displaying of SP Ramp Rate Value can be performed if parameter is enabled in Set-up Mode.

#### Display mode 1.



#### Display mode 2.







#### 10.7.2 MANUAL MODE

When manual mode is enabled **PDEn** = **Enob** in Set-up Mode, then press witten to enter manual mode



#### Caution!

Manual Mode should be used with care because the power output level is set by the operator, therefore the PID algorithm is no longer in control of the process. The operator must maintain the process as the desired level manually. Manual power is not limited by the **DPuL** (Primary Power Output Limit) parameter.

## **11. COMMUNICATION**

Some types of UNICONT PMM-500 controllers has RS485 communication module (as per order codes) (OUT A module). For a complete description of the Modbus protocol refer to the description provided at <a href="http://www.modbus.org">http://www.modbus.org</a>.

#### 11.1 GENERAL DATA

Type:	Asynchronous Serial
Protocol:	Modbus RTU
Physical Layer:	RS485
Address range:	1255
Bit rate:	120019200 Baud, selectable
Bits per character:	10 or 11, depending on parity setting
Stop bits:	1
Character format:	8 bit
Parity:	None, even or odd (selectable)
Isolation:	Reinforced safety isolation from inputs and outputs
Notal	

Note!

Device address, data transfer speed, parity, Communication write enable parameters (**Addr** , **Prot** , **bRud** , **CoEn**) can be selected in Configuration Mode.

The instrument is assigned a unique device address by the user in the range 1 (default) to 255 using the **Rddr** parameter in Configuration Mode. This address is used to recognise Modbus Queries intended for this instrument. The instrument will also accept global Queries using device address 0 no matter what device address is assigned. No responses are returned for globally addressed Queries. The transmitter must not start transmission until 3 character times have elapsed since reception of the last character in a message, and must release the transmission line within 3 character times of the last character in a message

DATA TRANSFER SPEED (BAUD)	3 CHARACTER TIMES (MSEC)
1200	24
2400	12
4800	6
9600	3
19200	1,5

## **11.2 MODBUS COMMUNICATION**

The unit uses the following Modbus functions:

MODBUS			
DECIMAL FUNCTION CODE	PARAMETER FORMAT	MODBUS MEANING	DESCRIPTION
01/02	Bit	Read coil/ Input status	Read output/input status bits at given address
03/04	Word	Read holding/Input registers	Read current binary value of specified number of parameters at given address. Up to 64 parameters can be accessed with one Query
05	Bit	Force single coil	Writes a single binary bit to the Specified Slave Bit address
06	Word	Pre-set single register	Writes two bytes to a specified word address
08	-	Diagnostics	Used for loopback test.
16	Word	Pre-set multiple register	Writes up to 1 word parameter values to the specified address range.

## **11.3 COMMUNICATION PARAMETERS**

Communication parameters RO indicates a parameter which is read only, R/W indicates it can also be written to. Communications writes will not implemented if the **LoEn** (Communications Write Parameter) is disabled in the Configuration Mode.

## 11.3.1 BIT PARAMETERS

MODBUS PARAMETER			NOTES	
NUMBER	MODE	CONTROLLING FARAMETER	NOTES	
1	RO	Communication Write Status	1 = Write Enabled 0 = Write Disabled	
2	R/W	Auto / Manual	1 = Manual Control 0 = Automatic Control	
3	R/W	Self Tune	1 = Activate(d) 0 = Dis-engage(d)	
4	R/W	Pre tune	1 = Activate(d) 0 = Dis-engage(d)	
5	RO	Alarm 1 Status	1 = Active 0 = Inactive	
6	RO	Alarm 2 Status	1 = Active 0 = Inactive	
7	R/W	Setpoint Ramping	1 = Enable(d) 0 = Disable(d)	
10	R/W	Loop Alarm Status	1 = Active/Enable 0 = Inactive/Disable	
12	R/W	Loop Alarm	Read to get loop alarm status. Write 0/1 to disable/enable	

Note:

To set the bit value to 1 write FF, to set the bit value to 0 write 00.

## 11.3.2 WORD PARAMETERS

MODBUS PARAMETER		CONTROLLING	NOTES	
NUMBER	MODE	PARAMETER	NOTES	
1	RO	Process Variable	Current value of PV If under-range = 62976,	
2	R/W	Setpoint	Value of currently selected setpoint.	
3	R/W	Output Power	0% to 100% for single output; -100% to +100% for dual output control. Bead Only if not in manual control.	
4	RO	Deviation	Difference between Process Variable and Setpoint (value = PV-SP)	
5	R/W	Secondary Proportional Band	Adjustable 0.0% to 999.9% of input span. Read only when Self-Tuning	
6	R/W	Primary Proportional Band	Adjustable 0.0% to 999.9% of input span. Read only when Self-Tuning	
7	R/W	Direct / Reverse Acting	1 = Direct Acting, 0 = Reverse	
8	R/W	Automatic Reset Time (or Loop Alarm Time)	Integral Time Constant value. (or Loop Alarm Time value in ON/OFF control mode if Loop Alarm Enabled) Read only if Self-Tuning. Modbus range: 0 to 5999	
9	R/W	Rate	Derivative Time Constant value. Read only if Self- Tuning. Modbus range: 0 to 5999	
10	R/W	Output 1 Cycle time	0.5, 1, 2, 4, 8, 16, 32, 64, 128, 256 or 512 seconds	
11	R/W	Scale Range Lower Limit	Lower limit of scaled input range selectable between-1999+9999	
12	R/W	Scale Range Upper Limit	Upper limit of scaled input range selectable between-1999+9999	
13	R/W	Alarm 1 Value	Alarm 1 active at this level	
14	R/W	Alarm 2 Value	Alarm 2 active at this level	
15	R/W	Manual Reset	Bias value. 0% to 100% for single control output or -100% to +100% for dual outputs	
16	R/W	Overlap / Deadband	20% to +20% of ( <b>Pb_P</b> + <b>Pb_S</b> ) Negative value = Deadband, Positive value = Overlap	
17	R/W	ON - OFF Differential	0.1% to 10.0% of input span Used for Primary output on/off differential and for combined Primary and Secondary on/off differential.	
18	R/W	Decimal Point Position	0 = xxxx, 1 = xxx.x, 2 = xx.xx, 3 = x.xxx Read only if not Linear Input	
19	R/W	Output 2 Cycle Time	0.5, 1, 2, 4, 8, 16, 32, 64,128, 256 or 512 seconds	
20	R/W	Primary Output Power Limit	Safety power limit; 0 to 100 %	
21	RO	Actual Setpoint	Current (ramping) value of selected setpoint	
22	R/W	Setpoint Upper Limit	Maximum setpoint value. Current SP to Input Range Maximum	
23	R/W	Setpoint Lower Limit	Minimum setpoint value. Current SP to Input Range Minimum	
24	R/W	Setpoint Ramp Rate	0 = OFF, 1 to 9999 increments / hour. Dec Point position as for input range.	
25	R/W	Input Filter Time Constant	0 to 100 seconds	
26	R/W	Process Value Offset	Modified PV = Actual PV + PV Offset. Limited by Scale Range Maximum and Scale Range Minimum -999+999	

MODBUS PARAMETER		CONTROLLING	NOTES
NUMBER	MODE	PARAMETER	NOTES
122	RO	Equipment ID	6100
123	RO	Interior code	4 characters
124	RO	Interior code	4 characters
125	RO	Interior code	4 characters
126	RO	Interior code	4 characters
129	RO	Interior code	16 characters
130	RO	Interior code	16 characters
133	RO	Input status	Input status. Read Only. Bit 0: Sensor break flag Bit 1: Under-range flag Bit 2: Over-range flag
2224	R/W	Option Slot 2 Re-transmit output Maximum	Maximum scale value for retransmit output in slot 2, -1999 to 9999
2225	R/W	Option Slot 2 Re-transmit output Minimum	Minimum scale value for retransmit output in slot 2, -1999 to 9999
2234	R/W	Option Slot 3 Re-transmit output Maximum	Maximum scale value for retransmit output in slot 3, -1999 to 9999
2235	R/W	Option Slot 3 Re-transmit output Minimum	Minimum scale value for retransmit output in slot 3, -1999 to 9999